TEQIP Workshop on Advanced Robotics [15-19 March 2016]

Feedback Form Centre for Mechatronics, IIT Kanpur

1. Was the theory taught in the workshop complemented by experiments?

Yes: 34

Additional comments:

- > Up to certain extent.
- ➤ Very beautifully.
- ➤ It does but not fully (obviously). Level of theory taught is for higher then experiments.
- Yes, it was & expert's with respective fields was very good.
- ➤ Not too much
- ➤ We require little more experiments & experimental time in the form of practice.
- > The theory was enough
- ➤ Theory of kinematics, dynamics of manipulator (multilink) parallel manipulator and many robotic system and demonstration is also needed.

2. Did the experiments cover the basics of the course?

Yes: 34

Additional Comments:

- > To some extent.
- ➤ Not too much extent
- ➤ This course cover basic as well as advance futural concepts too.
- ➤ It covers basic topics like actuator, sensors, simulators very well. Which I like most.

➤ Not actually the basic course experiments but the idea about is given within it.

3. Did you understand the experiments conducted in the laboratory in order to relate to robotics?

Yes: 34

- ➤ It is basically programming to input motion to robots.
- > Very much
- Some experiments we performed too though lab session duration was less. But whatever we saw, learn was helpful & good for research.
- ➤ I understand the experiment conducted in the laboratory in order to relate to robotics.
- ➤ How to control it & what actually happens.

4. Suggestions to improve the laboratory components of the course.

- > Instead of two laboratory session. It is better include more session.
- ➤ It's already developed
- ➤ One hour hands on experience should be given per day in the form of tutorials and/or software simulations.
- ➤ Include more experimental activities.
- ➤ Could have arranged some hands on robotics simulations softwares
- Please increase the duration of the lab course.
- > By increasing the time for laboratory session.
- ➤ Have whole 1 day or more for lab session.
- ➤ More lab session
- Actual robot format at least small one.
- ➤ In laboratory I became aware of some very good & amazing stuff so lab was good enough.
- ➤ Introduce to another course of spatial mechanisms and parallel robot or complaint mechanisms.

- ➤ Please try to use very cost equipments & the very general algorithm. So that, this may be also in the reach of maximum number of learners.
- ➤ A software based session (hands-on) for simulation and modelling.
- > Everything is good as per my level of knowledge.